

Welcome to the '06 Build Season!

Team 1720 thanks you for participating in our survey. We will make the results available on our website: www.team1720.org within the next week.

In the mean time here is your dongle.

What is it for?

1. It provides a way to DISABLE the robot from the Operator Interface.
2. It provides a way to test autonomous code.

Where do I plug it in?

The Operator Interface Competition port.

What about the switches?

There are 2 switches. One with a red toggle and the other with a chrome toggle.

Red Toggle: This is the Enable/Disable switch.

Toward the GREEN dot – Enable the robot

Toward the RED dot – disable the robot

Chrome Toggle: This is the Driver/Autonomous switch.

Toward WHITE – Normal driver controlled driving

Toward BLACK – Autonomous Mode

What else do I need to know?

The Enable/Disable switch must be in the GREEN position for either Driver or Autonomous mode to work.

When switched to Autonomous Mode (BLACK), the variable
`autonomous_mode` in

```
void User_Autonomous_Code(void) found in user_routines_fast.c
```

is TRUE.

Add your autonomous code after `Getdata(&rxdata);`

Good luck for the season!

For Team 1720, PhyXTGears

Mike Koch

Mentor

Mike.Koch@ontariosystems.com